Topology Control and Mobility Management in Mobile Ad Hoc Networks

Fei Dai and Jle Wu Department of Electrical and Computer Engineering North Dakota State University Department of Computer Science and Engineering Florida Atlantic University

Mobile Ad Hoc Networks

 Infrastructure-less multi-hop wireless networks formed by mobile nodes

Challenges

OFrequent topology changes

- Lack of central control
- Limited network resources
 - Energy
 - Bandwidth
 - Computing power



Topology Control (TC)

Goal

 Reduce transmission range (r) while maintaining network connectivity

Motivation

Energy efficiency

• $E_{Tx} \approx r^{\alpha}$ (2 $\leq \alpha \leq 4$) • r=10, single hop: $E_{Tx} \approx 1000$ (α =3) • r=1, 10 hops: $E_{Tx} \approx 10$ • Channel spatial reuse

• Interference Area $\approx r^2$

TC (Continued)

Method

- Each node collects information of 1-hop neighbors using "Hello" beacons
- Select a few logical neighbors from 1-hop neighbors
- Adjust transmission power to cover only logical neighbors

Logical Topology

 Virtual network formed by logical links (i.e., links between logical neighbors)

TC Example



Existing TC Protocols

- Select logical neighbors using local info.
 - ORelative neighborhood graph (RNG)
 - Minimal energy mobile wireless network and extensions (LSPT)
 - OLocal minimum spanning tree (LMST)
 - ○Yao graph
 - Cone-based topology control (CBTC)

Relative Neighbor Graph (Toussaint, 1980)



Yao Graph

- Divide neighborhood into 6 cones
- Select a nearest node from each cone as logical neighbor
- A special case of RNG
- Incremental search
 Until one neighbor detected in each cone



Minimal Energy Mobile Wireless Network (Rodoplu and Meng, 1999)

MEMWN OLogical neighbors forms a

closure

 $\bigcirc \forall$ outsider *j*, \exists insider *k*

s.t. $E_{i,j} > E_{i,k} + E_{k,j}$

Extension (Li and Halpern, 2001)

- Construct a shortest path from current node to each 1-hop neighbor w.r.t. Tx power
- First hop relays are logical neighbors



Cone-Based Topology Control (Li and Halpern, 2001)

Find k logical neighbors that are

- Nearest to the current node
- OThe maximal cone width θ≤2π/3
- Improve Yao graph
- Extension
 - Oθ≤4π/5 with some additional constraint



Local Minimal Spanning Tree (Li, Hou, and Sha, 2003)

LMST OFormed by shortest links Connect all 1-hop neighbors OLogical neighbors are MST neighbors In other words … ○ Remove link (*u*, *v*) if exist W_1, W_2, \ldots, W_k s.t. • $d_{u,v} > d_{u,w1}$ • $d_{u,v} > d_{w1,w2}$

$$\bullet d_{u,v} > d_{wk,v}$$



LMST Example



Local MSTs at nodes U, V, and W

Summary: Link Removal Rule

- Detect loops (*u*, *w*₁, *w*₂,..., *w*_k, *v*) within 1hop neighborhood
- Break loop by removing a link (u,v) with the highest cost C_{u,v}
- Some criteria break more loops than the others
- Guarantees connectivity in static networks
- What if the network is not static?

TC in Mobile Networks

Inaccurate position information

- Actual transmission range may not cover all logical neighbors
- Solution: slightly increase the actual transmission range (buffer zone)
- Inconsistent local view
 - OSimultaneous removal => disconnection
 - Oslution: enforce view consistency



 Link (v,w) is broken after w moves out of v's transmission range

Solution: Buffer Zone

- Increase the actual transmission range r by I to create a buffer zone that tolerate node movement
- I=dt, where t is the maximal relative moving speed, and d is the maximal delay
- Using a dt is possible



Inconsistent Local Views



Strong View Consistency (Wu and Dai, 2004)

- Solution
 - All nodes exchange "hello" messages at control period (h)
 - Decisions are made at the beginning of each data period (d)
- Problems
 - "Hello" message collision
 - Require synchronous clocks



Asynchronous Solution (Dai and Wu, 2005)

Enhanced local view

 Use history information

 Enhanced link removal rule

 Make conservative decisions

 Weak view consistency

 Guarantee connectivity in spite of mobility and asynchronous decision making

Enhanced Local View

Contain k recent "Hello" messages
 Up to k² cost values for each link (u,v)
 Max(C_{u,v}): maximum cost in current local view
 Min(C_{u,v}): minimum cost in current local view
 MinMax(C_{u,v}): minimum Max(C_{u,v}) in all local views
 MaxMin(C_{u,v}): maximum Min(C_{u,v}) in all local views



Enhanced Link Removal Rule

A link (u,v) can be removed, if

a loop (u, w₁, w₂,..., w_k, v) exist, and
Min(C_{u,v}) > Max(C_{u,wi}), Max(C_{w1,w2}), ..., Max(C_{wk,v})

Previous example reconsidered

Cannot remove (u,w): Min(C_{u,w}) < Max(C_{v,w})
Cannot remove (v,w): Min(C_{v,w}) < Max(C_{u,w})



Weak View Consistency

• Local views are weakly consistent, if $\bigcirc MinMax(C_{u,v}) \ge MaxMin(C_{u,v})$ for all (u,v)

Theorem: Applying enhanced link removal rule using weakly consistent local views guarantees connectivity

Theorem: Enhanced local views containing two recent "Hello" messages are weakly consistent.

Put together

OTwo "Hello" messages from each neighbor are enough to guarantees connectivity

Simulation

Simulator: ns2

Simulated algorithms

- OMST: local minimal spanning tree
- ORNG: relative neighborhood graph
- SPT: local shortest spanning tree with link cost d² (a=2) and d⁴ (a=4), where d is distance.
- Mobility model

○ Random waypoint, avg. speed 1-160m/s

- Ideal MAC layer without collision/contention
- Connectivity ratio: (pairs of connected nodes) / (total node pairs)

TC Protocols Under Mobile Environment



Buffer Zone Width

- Connectivity ratio increased as buffer zone width increases
- Buffer zone alone does not guarantee connectivity



Consistent Views

 Using consistent views improves connectivity ratio significantly



Conclusion

In MANETs, TC may cause

 Insufficient actual transmission power
 Disconnected logical topology

 Weak consistency scheme

 Guarantee connectivity using 2 recent "Hello" messages
 No synchronization overhead
 Slightly increase the number of logical links
 Enhance many existing TC protocols

Future directions

Fault tolerance against collision